DMG40960F040_01WTC DMG40960F040_01WTCZ01

Features:

- Based on T5L0, running DGUS II system.
- 4.0-inch, 400*960 pixels resolution, 262K colors, IPS-TFT-LCD, wide viewing angle.
- LCD and TP frame lamination process.
- Optional TP appearance of black and white.
- COF structure. The entire core circuit of the smart screen is fixed on the FPC of LCM, featured by light and thin structure, low cost and easy production.
- 50 pins, including IO, UART, CAN, AD and PWM from user CPU core for easy secondary development.





1 External Interface



User interface

PIN	Definition	I/O	Functional Description	
1	+5V	I		
2	+5V	I	Power supply, DC3.6-5.5V.	
3	GND	GND		
4	GND	GND	GND	
5	GND	GND		
6	AD7	I	5 input ADCs. 12-bit resolution in case of 3.3V power supply. 0-3.3V	
7	AD6	I	input voltage. Except for AD6, the rest data is sent to OS core via UART3 in real time with 16KHz sampling rate. AD1 and AD5 can be	
8	AD5	1	used in parallel, and AD3 and AD7 can be used in parallel, which equals to two 32KHz sampling AD. AD1, AD3, AD5, AD7 can be used in	
9	AD3 parallel, which equals to	parallel, which equals to a 64KHz sampling AD; the data is summed		
10	AD1	Т	1024 times and then divided by 64 to obtain a 64Hz 16bit AD value by oversampling.	
11	+3.3	0	3.3V output, maximum load of 150mA.	
12	SPK	0	External MOSFET to drive buzzer or speaker. The external 10K resistor should be pulled down to the ground to ensure that power-on is low level.	
13	SD_CD	10		
14	SD_CK	0		
15	SD_D3	10	SD/SDHC interface,The SD_CK connects a 22pF capacitor to GND	
16	SD_D2	10	near the SD card interface.	
17	SD_D1	10		
18	SD_D0	IO		
19	PWM0	о	2 16-bit PWM output. The external 10K resistor should be pulled down to the ground to ensure that power-on is low level.	
20	PWM1	O The OS core can be co	The OS core can be controlled in real time via UART3.	
21	P3.3	IO	If using RX8130 or SD2058 I2C RTC to connect to both IOs,	
22	P3.2	IO	SCL should be connected to P3.2,and SDA connected to P3.3 in parallel with 10K resistor pull-up to 3.3V.	

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23	P3.1/EX1	Ю	It can be used as an external interrupt 1 input at the same time, and supports both low voltage level or trailing edge interrupt modes.
24	P3.0/EX0	ю	It can be used as an external interrupt 0 input at the same time, and supports both low voltage level or trailing edge interrupt modes.
25	P2.7	IO	IO interface
26	P2.6	IO	IO interface
27	P2.5	IO	IO interface
28	P2.4	Ю	IO interface
29	P2.3	ю	IO interface
30	P2.2	Ю	IO interface
31	P2.1	IO	IO interface
32	P2.0	IO	IO interface
33	P1.7	IO	IO interface
34	P1.6	IO	IO interface
35	P1.5	Ю	IO interface
36	P1.4	IO	IO interface
37	P1.3	IO	IO interface
38	P1.2	IO	IO interface
39	P1.1	IO	IO interface
40	P1.0	Ю	IO interface
41	UART4_TXD	0	UART4
42	UART4_RXD	Ι	UAR14
43	UART5_TXD	0	UART5
44	UART5_RXD	Τ	
45	P0.0	ю	IO interface
46	P0.1	IO	IO interface
47	CAN_TX	0	CAN interface (External CAN chip drive is required .See 6 - (6) for circuit
48	CAN_RX	I	reference)
49	UART2_TXD	0	LIAPT2/LIAPT0 sorial part of OS care)
50	UART2_RXD	I	UART2(UART0 serial port of OS core)

2 Specification Parameters

2.1 Product Parameters

Main Chip	T5L0
User Interface	50Pin_0.5mm FPC
FLASH	8M Bytes
UI Version	DGUSII / TA
Power Supply	HDL662S adapter board power supply
Display Color	262K colors
Dimensions	4.0 inch
Resolution	400*960
Active Area	39.18mm (W)×94.03mm (H)
Viewing Angle	Wide viewing angel, typical value of 85°/85°/85°/85°(L/R/U/D)
Backlight Service Life	>10000 hours (Time of the brightness decaying to 50% on the condition of continuous working with the maximum brightness)
Brightness	250nit
Brightness Control	0~100 grade (When the brightness is adjusted to 1%~30% of the maximum brightness, flickering may occur and is not recommended to use in this range)
ТР Туре	CTP (Capacitive Touch Panel)
TP Structure	G+G structure
Touch Mode	Single point touch, support continuous sliding touch

	51 , 11 5
Surface Hardness	6Н
Light Transmittance	Over 90%
Life	Over 1,000,000 times touch

2.2 Interface Parameters Conditions Item Min Тур Max Unit **Baud Rate** User Set(Configure the CFG file) 3150 115200 3225600 bps V Output 1 3.0 3.3 -Output Voltage(TXD) Output 0 0 0.3 V _ Input 1 3.3 V --Input Voltage(RXD) Input 0 0 0.5 V -UART2: TTL; UART4: TTL; (Only available after OS configuration) Interface UART5: TTL; (Only available after OS configuration) UART2: N81; **Data Format** UART4: N81/E81/O81/N82;4 modes (OS configuration) UART5: N81/E81/O81/N82;4 modes (OS configuration)

2.3 Electrical specifications

Rated Power	<2W			
Operating Voltage	3.6~5.5V, typical value of 5V			
One setting Current	200mA	VCC=5V, max backlight		
Operating Current	90mA	VCC=5V, backlight off		
Recommended power supply	5V 0.5A DC			

2.4 Operating Environment

Operating Temperature	-10℃~60℃
Storage Temperature	-20℃~70℃
Operating Humidity	10%~90%RH, typical value of 60% RH

3 Reliability Test

The smart screen products undergo a series of procedural reliability tests, including high and low temperature, ESD, pulse and surge, and waterproof tests before mass production to ensure product quality.

3.1 ESD Test

Test temperature: 25°C

Test process: the product was placed on the test bench to perform contact and air discharge in turn of the serial screen iron frame and display area as shown in Fig.4.1 below. During the experimental process, it was observed whether the screen is dead, black, white, splash, or reboot. According to the experiment results, the performance is in line with the criteria GB/T 17626.2 B level and above.



4.1Electrostatic discharge test

Discharge Type	Discharge Value	Result Normal operation	
Contact discharge	±4KV		
Air discharge	±4KV	Normal operation	

3.2 High and Low Temperature Test

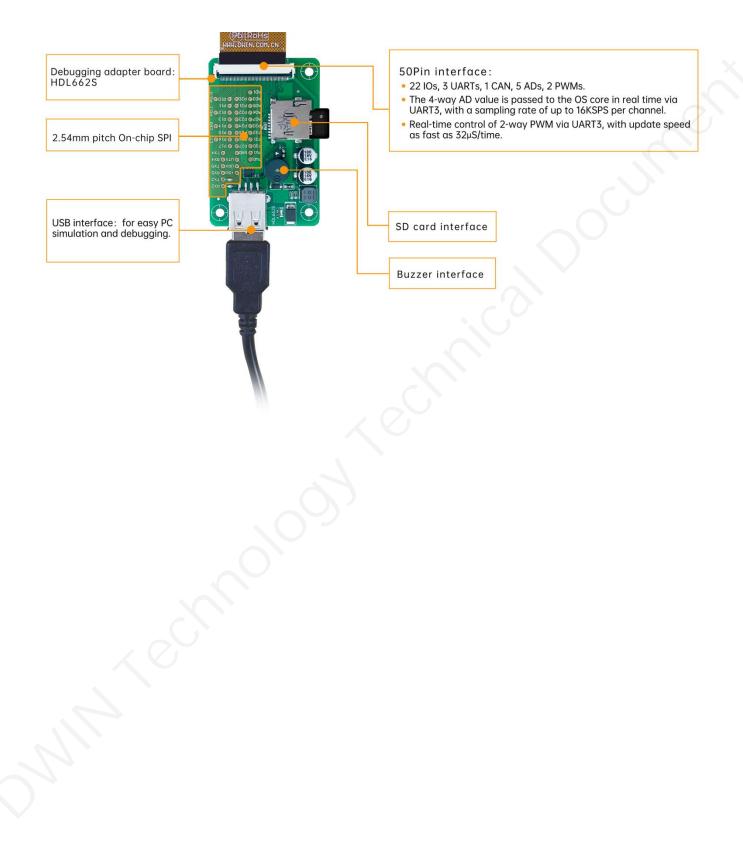
Test temperature:-20~70℃

Test process: the product will be placed obliquely in the high and low temperature test chamber for 12h for 20 on and off cycles. Then it will be check at room temperature after power on for the appearance and function, CTP offset situation, jumping point, page random switching and failure.

Temperature	Result
High temperature (70°C)	Normal operation
Low temperature (-20°C)	Normal operation

4 Debug

It is recommended for new users of DWIN smart LCMs to purchase official accessories. For more details, please refer to customer service center.



Operation steps: open serial assistant - custom function command - set command - send.

For example:

(1) Page switching

Tx: 5AA5 07 82 0084 5A01 0008

- (2) Standby backlight setting
 - Tx: 5AA5 07 82 0082 64 32 03E8

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	8×	Home 00.bmp					_
l Fictures	00	DwinPCKits				-	
: 00.bmp		Log	Qui	ek instructions	•		
: oo.omp			S	stem function instruction	Custon function instructions		
			[function	Custom instruction	send	cycle
				Write variable space	5a a5 04 82 10 00 01 22 33	send	
				Read variable space	5a a5 04 83 10 00 02	send	
				CPU reset	5a a5 07 82 00 04 55 aa 5a a5	send	
				Page switching	5AA5 07 82 0084 5A01 0008	send	
				Standby backlight setting	5AA5 07 82 0082 64 32 03E8	send	
						send	
					ļ	send	
						send	_
						send	
				1		send	100
				2		send	
				3		send	
				4		send	
				5		send	
				Automatic loop send interv	1 1000 1 10		
			Clear Log	Autowarte 1009 Sand, Interv	1000 V NS		
		Serial Fort Setting	Serial Port Order				
			○ Write VP	VP Address Ox 0	VF Length/Word On 1 0		

DGUS operation

5 T5L0 ASIC

T5L0 ASIC is a low-power, cost-effective, GUI and application highly integrated single-chip dual-core ASIC designed by DWIN Technology for small-size LCD and mass produced in 2020.

(1) Mature and stable 8051 core which is the most widely used with the maximum operating frequency of T5L is

up to 250MHz, 1T(single instruction cycle)high speed operation.

(2) Separate GUI CPU core running DGUS II System:

- High-speed display memory, 2.4GB/S bandwidth. 18-bit color display resolution support up to 1024*768 (TA mode), 854*480 (DGUS mode).
- 2D hardware acceleration and the UI with animation and icons as its main feature is extremely cool and smooth.
- Images and icons stored in JPEG format. Adopt Low-cost 16Mbytes SPI Flash.
- High quality ratio and sound restoration and playback.
- 128Kbytes variable storage space for exchanging data with OS CPU Core and memory.
- 2 10-bit 800KHz DC/DC controllers simplify LED backlight, analog power design and save cost and space.
- Support DGUS development and simulation on PC. Support backend remote upgrade.

(3) Separate CPU (OS CPU) core runs user 8051 code or DWIN OS system and user CPU is omitted in

practical application:

- Standard 8051 core and instruction set, 64Kbytes code space, 32Kbytes on-chip RAM.
- 64-bit integer mathematical operation unit (MDU), including 64-bit MAC and 64-bit divider.
- Built-in software WDT, 3 16-bit Timers, 12 interrupt signals support up to four levels of interrupt nesting.
- Support IAP online simulation and debugging with unlimited breakpoints.
- Upgrade code online through DGUS system.
- (4) 1Mbytes on-chip Flash with DWIN patent encryption technology ensure code and data security.

(5) Operating temperature ranges from -40 $^{\circ}$ C to +85 $^{\circ}$ C (IC operating temperature customizable from -55 $^{\circ}$ C to 105 $^{\circ}$ C).

(6) Low power consumption and strong anti-interference ability. It can work stably on double-sided PCB and passes EMC/EMI test easily.

6 COF Screen Secondary Development

Standard 8051 core, easy to develop in C language and assembly language.

(1) 22 IOs:

To use output function of IO, you need to open the output control, output strength and peripheral multiplexing power-on initialization configuration. Subsequent use of IO is consistent with the standard 8051 as follows.

```
#include "sys.h"
sbit LED1 = P1^0;
sbit KEY1 = P1^1;
//Pin initialization
void io init()
         PORTDRV = 0x01;//Driving current is 8mA
         P1MDOUT |= 0x01;//Set P1.0 as output to drive LED1 light
        P1MDOUT &= 0xFD;//Set P1.1 as input to read the voltage level change of the pin
void main(void)
         u16 cnt_1ms;
        u16 key1_sta;//Store the voltage level state of the KEY1 pin
         sys init();//System initialization
        io_init();//Pin initialization
        cnt 1ms = 0;
         key1 sta = KEY1;
        while(1)
         {
                 cnt 1ms++;
                  sys_delay_ms(1);// Delay sub-function, LED1 blinks every 500ms.
                  if(cnt_1ms==500)
                  {
                           LED1 = !LED1;
                           cnt 1ms = 0;
                  //If the voltage level of the pin has changed, it will be updated in the interface
                 if(key1_sta!=KEY1)
                  {
                           key1 sta = KEY1;
                           sys_write_vp(0x1000,(u8*)&key1_sta,1);
                 }
        }
```

(2) 3 UARTs:

High-speed serial port, supporting up to 3225600bps,as follows.

```
#include "sys.h"
#include "uart2.h"
void main(void)
        u16 len;
        sys init();//System initialization
        uart2_init(115200);//Initialize serial port 2
        while(1)
        Ł
                  if(uart2_rx_sta&UART2_PACKET_OK)//Received serial packet
                           len = uart2 rx sta&UART2 PACKET LEN;//Get the length of the serial packet without "\r\n"or '\n' terminator
                           uart2_buf[len++] = 0;//Add 2 empty strings at the end
                           uart2_buf[len++] = 0;
                           printf("T5L_C51:%s\r\n",uart2_buf);//Return the received packet to the sender with the prefix "T5L_C51:"
                           sys_write_vp(0x2000,uart2_buf,len/2+1);//At the same time display the packet to the interface
                           uart2_rx_sta = 0;//Reset means that this serial packet is disposed of
                 }
        }
```

(3) 1 CAN:

Only the special function registers of the CAN need to be configured as follows.

void CanInit()

P0MDOUT = 0x04; //P0.2(CAN_TX) is configured as output
P0 = 0xFF; //Output high voltage level
ADR H = 0xFF; //Configuring DGUS variable memory addresses
ADR_M = 0x00;
ADR L = 0x60;
ADR INC = 1; //Configure address increments
RAMMODE = 0x8F; //Write mode
while(!APP_ACK); //Waiting for confirmation, Among answers of Hardware to 8051 occupied variable memory request,
1=OK and 0=BUSY, which need to continue to wait.
DATA3 = 0x1A; //Variable memory address 0xFF:0060 assignment
DATAS = 0x17; DATAS = 0x17;
DATA2 = 0x17, DATA1 = 0x0F;
·
APP_EN = 1;
while(APP_EN); //Wait for the data operation to be completed, and reset after the operation is completed
DATA3 = 0; //Acceptance register 0xFF:0061 assignment reset
DATA1 = 0;
APP_EN = 1;
while(APP_EN); //Wait for the data operation to be completed, and reset after the operation is completed
DATA3 = 0xFF; //Acceptance Mask Register 0xFF:0062 all set to 1, and no acceptance of reception
DATA2 = 0xFF;
DATA1 = 0xFF;
DATA0 = 0xFF;
APP_EN = 1;
while(APP_EN); //Wait for the data operation to be completed, and reset after the operation is completed
RAMMODE = 0; //Terminate access to DGUS variable memory
CAN_CR = 0xA0; //Open CAN and configure FF0060-FF0062
while(CAN_CR&0x20); // Execute the configuration of FF0060-FF0062
ECAN = 1; //Open the CAN interrupt
EA = 1; //Open the total interrupt

(4) 5 A/Ds: 12-bit, supports sampling to 16-bit

Only the special function registers of the A/Ds need to be configured as follows.

```
#include "sys.h"
#include "adc.h"
void main(void)
{
    u16 ad;
    float vol;
    sys_init();//System initialization
    while(1)
    {
        ad = adc_read_avg(ADC_CHANNEL0,10);//1.Read the ad value of channel 0
        vol = ad*(3300.0f/4095);//2.Calculate the voltage in mV
        sys_write_vp(0x2000,(u8*)&ad,1);// Update the ad value
        sys_write_vp(0x2001,(u8*)&vol,2);//Update the voltage value
    }
}
```

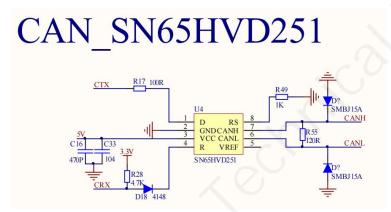
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(5) 2 PWMs: 16-bit high accuracy, adjustable resolution.

Only need to configure the frequency and duty cycle of PWM as follows.

```
void Pwm_0()
{
    u8 i=0;
    u8 temp[6]={0xAA,0x20,0x42,0x56,0x78,0};//Set the pwm_0 duty cycle to 100%
    Write_Dgus(0x87,0x2042);//Configure the frequency100khz
    Write_Dgus(0x86,0x5A01);//
    for(i=0;i<5;i++) //Checksum
        temp[5]+=temp[i];
    for(i=0;i<6;i++)//Configure the duty cycle
        OneSendData3(temp[i]);</pre>
```

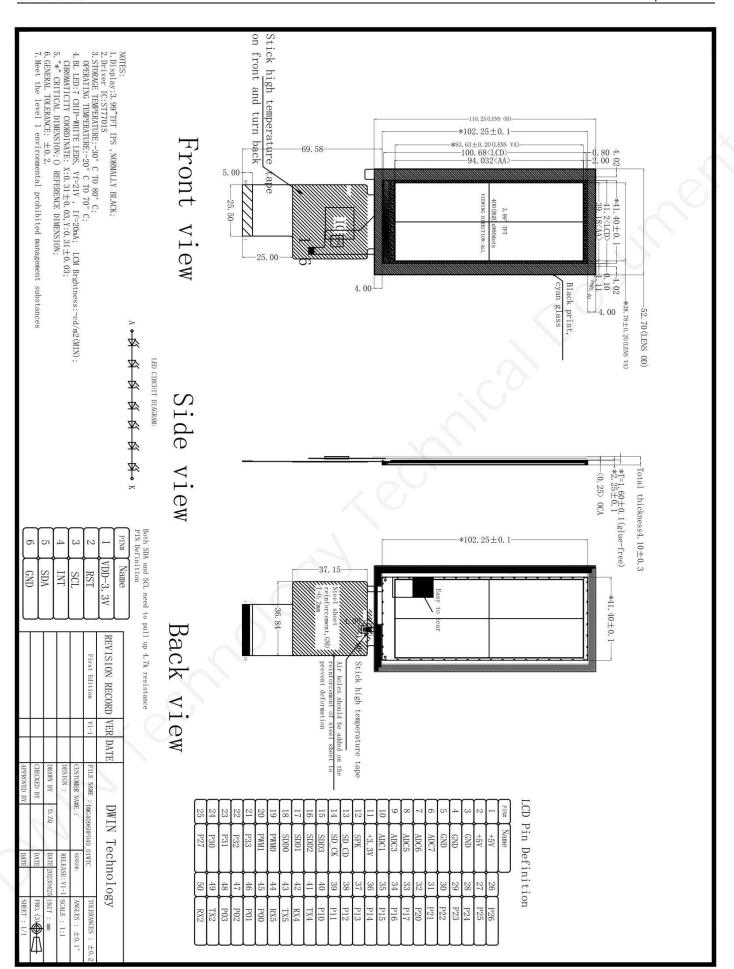
(6) CAN circuit design parameters

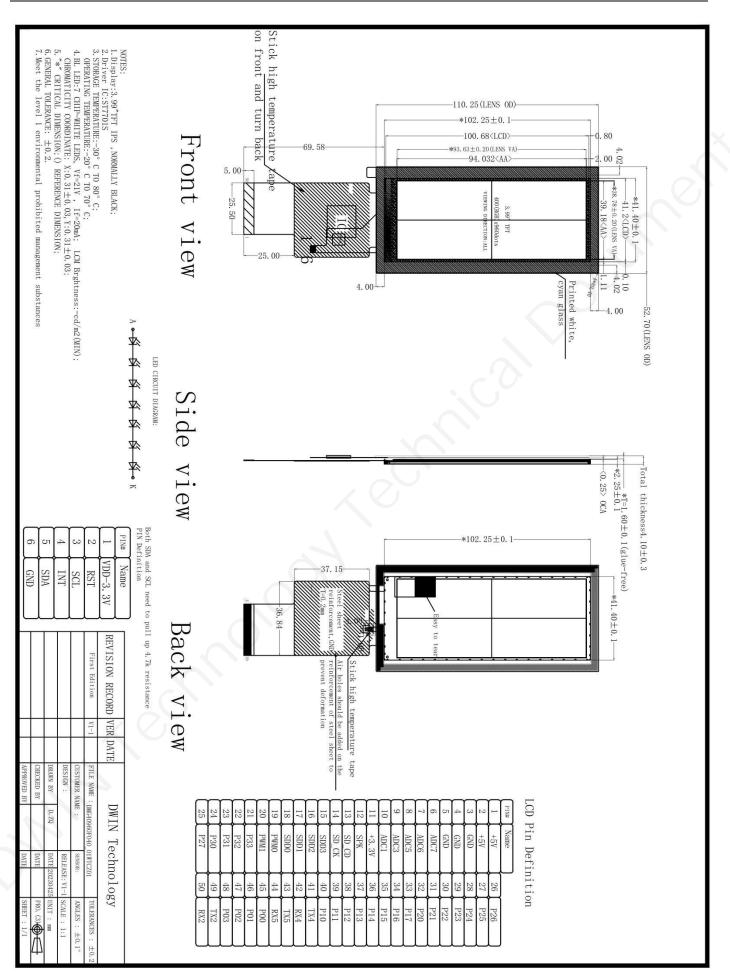


7 Packing Capacity & Dimension

Dimension					
Dimension	52.70(W) ×110.25(H) × 4.10(T) mm				
Net Weight	45g				
Packing Capacity	Packing Capacity				
Model	Size Layer Quantity/Layer Quantity(Pcs)				
Carton1:	220mm(L)×160mm(W)×47mm(H)	1	4	4	
Carton2:	250mm(L)×200mm(W)×80mm(H)	1	8	8	
Carton3:	320mm(L)×270mm(W)×80mm(H)	1	16	16	
Carton4:	450mm(L)×350mm(W)×300mm(H)	2	60	120	
Carton5:	600mm(L)×450mm(W)×300mm(H)	3	80	240	

Disclaimer: The product design is subject to alternation and improvement without prior notice.





8 Revision records

Rev Revise Date		Content	Editor	
00	2023-05-16	First Edition	Xu Ying	

Please contact us if you have any questions about the use of this document or our products, or if you would like to know the latest information about our products:

- Customer service Tel: +86 400 018 9008
- Customer service email: dwinhmi@dwin.com.cn
- DWIN Developer Forum: <u>https://forums.dwin-global.com/</u>

Thank you all for continuous support of DWIN, and your approval is the driving force of our progress!